

Law and Economics  
Session 4  
The Basic Model of Legal Incentives

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June 2, 2014

# A basic model of legal incentives

- The theme of this course is that with just a few concepts, economics can unify many different legal doctrines.
- In particular, the key insights of property, contracts, torts, and criminal law can be captured in a unified framework.

- Rancher  $A$ , Farmer  $B$ , Farmer chooses fence  $x \in \{0, 1\}$ , payment  $w$ .
- Payoffs:

$$u_A = \omega_A + w - ax$$

$$u_B = \omega_B - w + bx$$

- Regime 1 versus Regime 2.
- Costless negotiation between the neighbors.
- When  $b > a$ , parties ended up having the fence built under both regimes.
- When  $a > b$ , no fence under either regime.

# Contract Law Example

- Seller  $A$ , Buyer  $B$ , contract specifies quality  $\tilde{x}$ , payment  $w$
- Payoffs:

$$u_A = w - ax$$

$$u_B = b(x) - w$$

- With expectations damages  $z = b(\tilde{x}) - b(x)$  for  $x < \tilde{x}$ , seller's utility function becomes

$$u_A = w - ax - b(\tilde{x}) + b(x)$$

for  $x < \tilde{x}$  and  $w - ax$  for  $x = \tilde{x}$ , giving incentives to set  $x = \tilde{x}$ .

- Injurer  $A$ , Victim  $B$ , injurer chooses precaution  $x \geq 0$  but probability  $1 - p(x)$  of harm to  $B$
- Payoffs:

$$u_A = \omega_A - ax$$

$$u_B = \begin{cases} \omega_B & \text{(no accident)} \\ \omega_B - b & \text{(accident occurs)} \end{cases}$$

$$\mathbb{E}(u_B) = \omega_B - (1 - p(x))b$$

- The tort rule of full compensation for damages to victim results in

$$\mathbb{E}(u_A) = \omega_A - ax - (1 - p(x))$$

which gives efficient precaution incentives.

- Criminal  $A$ , Victim  $B$ , criminal chooses crime  $x \geq 0$ , govt chooses enforcement  $y$ , prob.  $1 - p(x, y)$  criminal is caught.
- Payoffs:

$$u_A = \begin{cases} ax & \text{(undetected)} \\ ax - b(x) & \text{(detected)} \end{cases}$$

$$\mathbb{E}(u_A) = ax - (1 - p(x, y))b(x)$$

- Chosen crime level  $x^*(y)$  solves

$$a = p_x(\cdot)b(\cdot) + p(\cdot)b_x(\cdot)$$

- Social welfare function:

$$W = \omega - y - x^*(y)$$

- Socially optimal enforcement requires

$$1 = -\frac{\partial x^*(y)}{\partial y}$$